

apogee

INSTRUMENTS

OWNER'S MANUAL

OXYGEN SENSOR

Models SO-411 and SO-421

Rev: 28-Oct-2020



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CERTIFICATE OF COMPLIANCE

EU Declaration of Conformity

This declaration of conformity is issued under the sole responsibility of the manufacturer:

Apogee Instruments, Inc.
721 W 1800 N
Logan, Utah 84321
USA

for the following product(s):

Models: SO-411, SO-421
Type: Oxygen Sensor

The object of the declaration described above is in conformity with the relevant Union harmonization legislation:

2014/30/EU Electromagnetic Compatibility (EMC) Directive
2011/65/EU Restriction of Hazardous Substances (RoHS 2) Directive
2015/863/EU Amending Annex II to Directive 2011/65/EU (RoHS 3)

Standards referenced during compliance assessment:

EN 61326-1:2013 Electrical equipment for measurement, control and laboratory use – EMC requirements
EN 50581:2012 Technical documentation for the assessment of electrical and electronic products with respect to
the restriction of hazardous substances

Please be advised that based on the information available to us from our raw material suppliers, the products manufactured by us do not contain, as intentional additives, any of the restricted materials including lead (see note below), mercury, cadmium, hexavalent chromium, polybrominated biphenyls (PBB), polybrominated diphenyls (PBDE), bis(2-ethylhexyl) phthalate (DEHP), butyl benzyl phthalate (BBP), dibutyl phthalate (DBP), and diisobutyl phthalate (DIBP). However, please note that articles containing greater than 0.1% lead concentration are RoHS 3 compliant using exemption 6c.

Further note that Apogee Instruments does not specifically run any analysis on our raw materials or end products for the presence of these substances, but rely on the information provided to us by our material suppliers.

Signed for and on behalf of:
Apogee Instruments, October 2020



Bruce Bugbee
President
Apogee Instruments, Inc.

INTRODUCTION

Oxygen (O₂) is the second most abundant gas in the atmosphere and is essential to life on Earth. Oxygen availability determines the rate of many biological and chemical processes and is required for aerobic respiration. As described in this manual, it is the absolute amount of oxygen (measured as partial pressure in kilopascals) that nearly always determines oxygen availability, but we think of oxygen as a percent of the total number of molecules in the air (20.95 %). The best example of this is the oxygen on top of Mount Everest, which is 20.95 %, but most climbers need supplemental oxygen to get to the top.

There are two types of oxygen sensors: those that measure gaseous O₂ and those that measure dissolved oxygen in a solution. The Apogee sensor measures gaseous O₂.

There are multiple techniques for measuring gaseous oxygen. Three widely used approaches for environmental applications are galvanic cell sensors, polarographic sensors, and optical sensors. **The Apogee sensor is a galvanic cell type.** Galvanic cell and polarographic sensors operate by electrochemical reaction of oxygen with an electrolyte, which produces an electrical current. The electrochemical reaction consumes a small amount of oxygen. Unlike polarographic oxygen sensors, galvanic cell sensors are self-powered. Optical oxygen sensors use fiber optics and a fluorescence method to measure oxygen via spectrometry.

Typical applications of Apogee oxygen sensors include measurement of oxygen in laboratory experiments, monitoring gaseous oxygen in indoor environments for climate control, monitoring of oxygen levels in compost piles and mine tailings, and determination of respiration rates through measurement of oxygen consumption in sealed chambers or measurement of oxygen gradients in soil/porous media. Apogee oxygen sensors are not intended for use as medical monitoring devices.

Apogee Instruments SO-400 series oxygen sensors consist of a galvanic cell sensing element (electrochemical cell), Teflon membrane, reference temperature sensor (thermistor), heater (located behind the Teflon membrane), signal processing circuitry (mounted in a polypropylene plastic housing), and a cable to connect the sensor to a measurement device. Sensors are designed for continuous gaseous oxygen measurement in ambient air, soil/porous media, sealed chambers, and in-line tubing (flow through applications). SO-400 series oxygen sensors output gaseous oxygen data via the SDI-12 digital protocol.

SENSOR MODELS

Model	Output	Response	Temperature Sensor
SO-411	SDI-12	Standard Response	Thermistor
SO-421	SDI-12	Fast Response	Thermistor
SO-110	Analog	Standard Response	Thermistor
SO-120	Analog	Standard Response	Thermocouple
SO-210	Analog	Fast Response	Thermistor
SO-220	Analog	Fast Response	Thermocouple

The standard response sensor (SO-411) is designed for use in soil/porous media. It has a longer expected lifetime than the fast response sensor (SO-421), which is designed for use in flow through applications.



Sensor model number, serial number, and production date are located on a label between the sensor and pigtail lead wires.

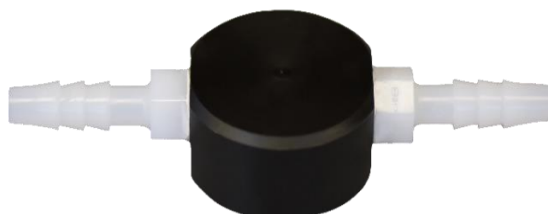
Accessories

All Apogee oxygen sensors can be purchased with attachments to facilitate measurements in soil/porous media or in-line tubing.

Model AO-001: Diffusion head designed for measurements in soil/porous media. The diffusion head maintains an air pocket and provides protection to the permeable Teflon membrane where gas diffusion occurs.



Model AO-002: Flow through head designed for in-line measurements. The flow through head allows connection of tubing via ¼ inch barbed nylon connectors.



SPECIFICATIONS

	SO-411 Standard Response	SO-421 Faster Response
Input Voltage Requirement	5.5 to 24 V DC	
Current Draw	0.6 mA (quiescent); 1.3 mA (active)	
Measurement Range	0 to 100 % O ₂	
Measurement Repeatability	Less than 0.1 % of mV output at 20.95 % O ₂	
Non-linearity	Less than 1 %	
Long-term Drift (Non-stability)	1 mV per year	0.8 mV per year
Oxygen Consumption Rate	0.1 μmol O ₂ per day at 20.95 % O ₂ and 23 C (galvanic cell sensors consume O ₂ in a chemical reaction with the electrolyte, which produces an electrical current)	
Response Time	60 s	14 s
Operating Environment	-20 to 60 C; 0 to 100 % relative humidity (non-condensing); 60 to 114 kPa Note: Electrolyte will freeze at temperatures lower than -20 C. This will not damage the sensor, but the sensor must be at a temperature of -20 C or greater in order to make measurements.	
Input Voltage Requirement	12 V DC continuous (for heater); 2.5 V DC excitation (for thermistor)	
Heater Current Draw	6.2 mA (74 mW power requirement when powered with 12 V DC source)	
Thermistor Current Draw	0.1 mA DC at 70 C (maximum, assuming input excitation of 2.5 V DC)	
Dimensions	32 mm diameter, 68 mm length	
Cable	5 m of four conductor, shielded, twisted-pair wire, additional cable available in multiples of 5 m; TPR jacket (high water resistance, high UV stability, flexibility in cold conditions); pigtail lead wires	
Mass	175 g (with 5 m of lead wire)	
Warranty	4 years against defects in materials and workmanship	

Influence from Various Gases: Sensors are unaffected by CO, CO₂, NO, NO₂, H₂S, H₂, and CH₄. There is a small effect (approximately 1 %) from NH₃, HCl, and C₆H₆ (benzene). Sensors are sensitive to SO₂ (signal responds to SO₂ in a similar fashion to O₂). Sensors can be damaged by O₃.

DEPLOYMENT AND INSTALLATION

Apogee SO-400 series oxygen sensors are built with a polypropylene plastic housing and are designed to be installed in soil/porous media or sealed chambers, in addition to air.



Note: To facilitate the most stable readings, sensors should be mounted vertically, with the opening pointed down and the cable pointed up. This orientation allows better contact between the electrolyte and signal processing circuitry.

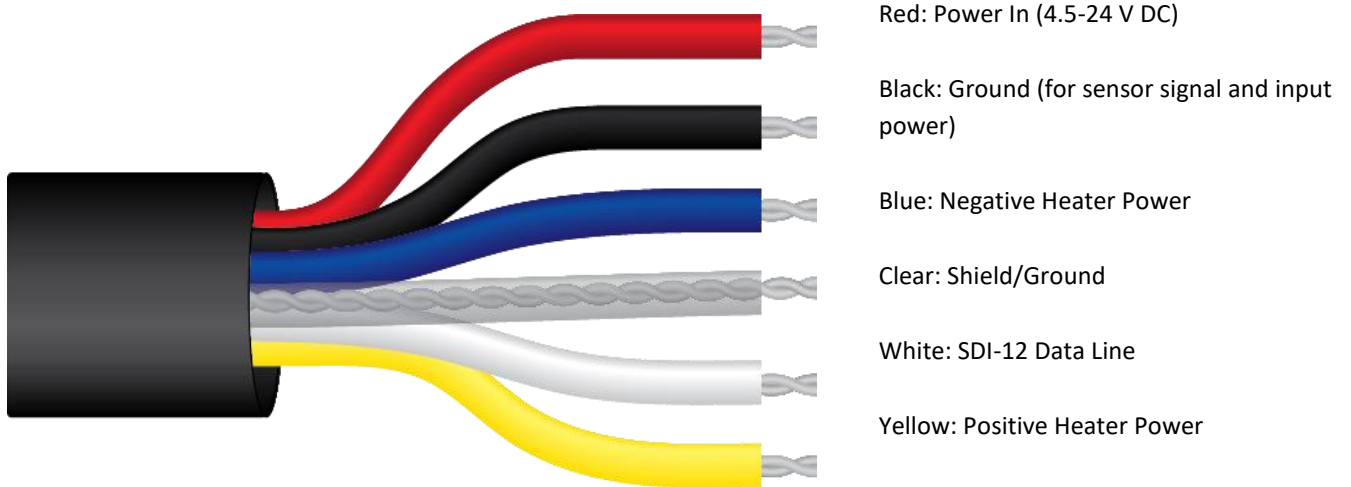
Apogee oxygen sensors are resistant to 2.7 G of shock, but vibration may influence sensor sensitivity and should be minimized.

OPERATION AND MEASUREMENT

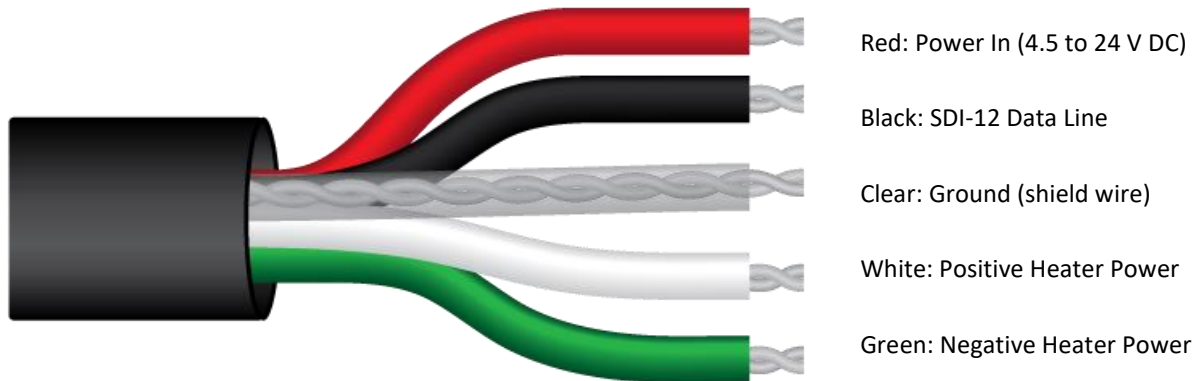
All SO-400 series oxygen sensors have an SDI-12 output, where oxygen measurements and temperatures are returned in digital format. Measurement of the SO-400 series oxygen sensors requires a measurement device with SDI-12 functionality that includes the M or C command.

VERY IMPORTANT: Apogee changed all wiring colors of our bare-lead sensors in March 2018 in conjunction with the release of inline cable connectors on some sensors. To ensure proper connection to your data device, please note your serial number or if your sensor has a stainless-steel connector 30 cm from the sensor head then use the appropriate wiring configuration below.

Wiring for SO-400 Series with Serial Numbers 1145 and above



Wiring for SO-400 Series within Serial Number range 0- 1144



ABSOLUTE AND RELATIVE GAS CONCENTRATION

Gas concentration is described in two ways, absolute and relative concentration. The ideal gas law yields absolute gas concentration, often expressed in quantity per volume [mol m^{-3}] or partial pressure [kPa]:

$$PV = nRT \quad (1)$$

where P is pressure [Pa], V is volume [m^3], n is gas quantity [mol], T is temperature [K], R is the ideal gas constant ($8.314 \text{ J mol}^{-1} \text{ K}^{-1}$), and rearrangement of equation (1) to solve for n / V or P yields absolute gas concentration (in mol m^{-3} or kPa, respectively). However, a simple and common way to report concentration of a specific gas in a mixture is by expressing it relative to other gases in the mixture, as a fraction or percentage. For example, the amount of oxygen in the atmosphere, assuming a dry atmosphere (no water vapor), is 0.2095 kPa O_2 per kPa air, or 20.95 %. Atmospheric concentration of oxygen has remained constant for several hundred years at 20.95 %, and this percentage is the same at all elevations. However, absolute oxygen concentration does not remain constant (e.g., pressure decreases with elevation, thus, absolute oxygen concentration decreases with elevation). Absolute oxygen concentration determines the rate of most biological and chemical processes, but relative oxygen concentration is often reported. This is analogous to measuring and reporting relative humidity when absolute humidity is what determines evaporation rates. Absolute and relative gas concentration measurements can be expressed using several different units.

Units Used to Describe Absolute and Relative Gas Concentration Measurements

Absolute Amount of Gas	Relative Amount of Gas
moles of O_2 per unit volume (e.g., moles per m^3 or moles per liter)	% O_2 in air (e.g., 20.95 % in ambient air)
mass of O_2 per unit volume (e.g., grams per liter; O_2 has a mass of 32 g per mole)	mole fraction (e.g., moles of O_2 per mole of air; 0.2095 mol O_2 per mole of ambient air; this can also be expressed as 0.2095 kPa O_2 per kPa air)
partial pressure (e.g., kilopascals [kPa])	

Sensor Calibration

All Apogee oxygen sensors respond to absolute oxygen concentration in air, where common units of absolute gas concentration are partial pressure (e.g., kilopascals, kPa), mass per unit volume (e.g., grams per liter, g l^{-1}), and number of molecules per unit volume (e.g., moles per liter, mol l^{-1}). The absolute amount of oxygen in air is dependent on absolute (barometric) pressure and temperature, in addition to oxygen content of air. Therefore, Apogee oxygen sensors are not calibrated at the factory and must be calibrated by the user, where an onsite calibration before first use is highly recommended.

The output of Apogee oxygen sensors is a linear function of absolute oxygen concentration. A simple linear calibration is generally used to derive a calibration factor used to convert sensor output to relative oxygen concentration. The calibration factor (CF, in $\text{kPa O}_2 \text{ mV}^{-1}$) is derived by dividing ambient oxygen partial pressure (21.23 kPa at sea level assuming standard pressure of 101.325 kPa) by the measured voltage output from the sensor under ambient conditions (in air or over water in a sealed chamber) minus the measured voltage output under conditions of zero oxygen (0 kPa O_2):

$$CF = \frac{0.2095 P_B}{mV_C - mV_0} \quad (2)$$

where P_B is barometric pressure [kPa], 0.2095 multiplied by P_B equals partial pressure of oxygen under ambient conditions [kPa], mV_C is sensor voltage output [mV] during calibration, mV_0 is sensor voltage output [mV] under zero oxygen (0 kPa O_2), and CF is a linear multiplier that converts voltage measurements from the sensor to partial pressure of oxygen [kPa] using the equation:

$$O_2 = CF \cdot mV_M - \text{Offset} \quad (3)$$

where mV_M is measured voltage output [mV] and Offset is derived by multiplying CF by mV_0 . The voltage output during calibration, mV_C , should be measured in a well-ventilated area. Do not breathe on the sensor, as exhaled breath has a much lower oxygen concentration than ambient air. If mV_0 is not measured, it can be estimated to be 3.0 mV for SO-411 sensors and 0.30 mV for SO-421 sensors. It is recommended that mV_0 be measured (in pure nitrogen gas) for applications where low values of oxygen (less than 10 kPa) will be measured. Precise measurements of hypoxic and anaerobic conditions can be made by making a periodic zero calibration of the sensor with ultra-pure nitrogen gas.

To convert sensor voltage output to partial pressure of oxygen (in kPa), multiply the measured voltage signal by the calibration factor, and then subtract the offset. For example, at sea level and 20.95 % O_2 :

Calibration Factor [kPa O_2 per mV] * Sensor Output Signal [mV] - Offset [kPa] = Oxygen [kPa]

$$0.379 \quad * \quad 59.0 \quad - \quad 1.14 \quad = \quad 21.23$$

The calibration factor and offset are variable from sensor to sensor (those listed above are examples), and a sensor-specific calibration factor should be derived for each individual sensor. For routine oxygen measurements, the generic offset described above can be used. For measurements in air with less than 10 kPa (approximately 10 %) oxygen, a sensor-specific offset should be derived for each individual sensor.

Sensors can also be calibrated to measure relative oxygen concentration. The same procedure described for calibration to absolute oxygen is used, except ambient oxygen is set equal to 20.95 % (instead of 0.2095 multiplied by barometric pressure) to derive the calibration factor [% O_2 mV^{-1}]:

$$CF = \frac{20.95\%}{mV_C - mV_0} \quad (4)$$

where mV_C and mV_0 are as described above. The offset is also derived in the same manner, where mV_0 is multiplied by the calibration factor calculated from equation (4). Equation (3) is then used to produce relative oxygen measurements, when the calibration factor and offset derived from 20.95 % are used.

Changes in barometric pressure and temperature cause changes in absolute oxygen concentration, and as a result, changes in sensor signal output. This causes apparent changes in relative oxygen concentration, even though the relative amount of oxygen remains constant. Thus, barometric pressure and temperature corrections must be applied to relative oxygen measurements. Changes in absolute humidity (water vapor pressure of air) cause changes in absolute and relative oxygen concentration, as water vapor molecules displace and dilute oxygen molecules. Even though changes in water vapor content cause actual (not apparent) changes in relative oxygen concentration, water vapor effects are often corrected for to yield relative oxygen concentrations for a dry atmosphere.

Effect of Barometric Pressure on Oxygen Concentration

The ideal gas law, equation (1), shows that absolute gas concentration increases by 0.987 % at sea level for every 1 kPa increase in pressure (1 kPa / 101.325 kPa = 0.00987). For a sensor that measures absolute gas concentration, but is calibrated to read out in relative units, a 1 kPa pressure increase at sea level results in an apparent oxygen increase of 0.207 % (0.00987 * 20.95 % = 0.207 %) and an apparent relative oxygen concentration of 21.157 %. Relative gas concentration didn't really increase, but absolute concentration, which is what sensors measure, did change. This shows up as an apparent change in relative concentration.

Due to lower barometric pressure at higher elevations, the percentage increase in absolute gas concentration per kPa increases with elevation. For example, at an elevation of 1378 m (Logan, Utah), barometric pressure is approximately 86 kPa and absolute gas concentration increases by 1.16 % for every 1 kPa increase in pressure (1 kPa / 86 kPa = 0.0116). Again, for a sensor that measures absolute gas concentration, but is calibrated to read out in relative units, this results in an apparent oxygen increase. In this example, 0.247 % for every 1 kPa increase in barometric pressure (0.0116 * 20.95 % = 0.243 %) and an apparent relative oxygen concentration of 21.193 %.

A barometric pressure correction should be applied to all oxygen sensors that are calibrated to read relative oxygen concentration. The equation to correct relative oxygen measurements for barometric pressure at any elevation is:

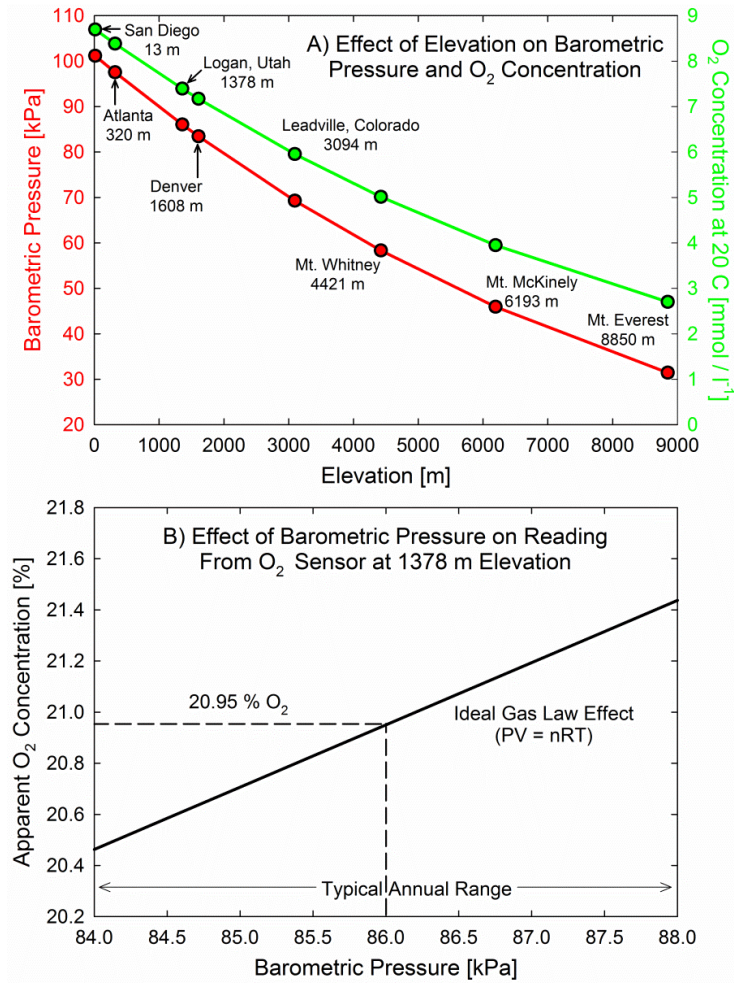
$$O_2 = O_{2M} \left(\frac{P_C}{P_M} \right) \quad (5)$$

where O_{2M} is measured oxygen concentration [%] (apparent oxygen concentration), P_C is barometric pressure [kPa] at the time of calibration, and P_M is barometric pressure [kPa] at the time of the current measurement. Approximate barometric pressure (P_B , in kPa) for a given elevation is calculated from:

$$P_B = 101.325 - 101.325 \left[1 - \left(1 - \frac{E}{44307.69231} \right)^{5.25328} \right] \quad (6)$$

where E is elevation [m]. In order to make a barometric pressure correction on gas measurements, it must be continuously measured as it changes over time (see Apogee webpage for a barometric pressure sensor that can be used for continuous measurements of barometric pressure: <http://www.apogeeinstruments.com/barometric-pressure/>). The typical annual barometric pressure range is approximately 4 kPa, or the average pressure for a given elevation +/- 2 kPa.

The apparent effect of barometric pressure on relative oxygen measurements, based on calculations from equation (5), is plotted in the figure below for 1378 m elevation to show the significance of measuring and correcting for barometric pressure. If not accounted for, barometric pressure fluctuations show up in oxygen measurements as a change in relative oxygen concentration because sensors respond to absolute oxygen concentration, but are generally calibrated to read out in relative units.



A) Barometric pressure and absolute oxygen concentration at 20 C as a function of elevation. Equation (6) was used to calculate barometric pressure.

B) Effect of barometric pressure on apparent relative oxygen concentration. Oxygen sensors respond to absolute oxygen concentration, but are often calibrated to yield relative oxygen concentration. As barometric pressure fluctuates, absolute oxygen concentration, thus, oxygen sensor output, fluctuates with it, producing an apparent change in relative oxygen concentration if this pressure effect is not accounted for. It is assumed the sensor was calibrated at 86 kPa, and the solid line shows how the apparent relative oxygen concentration is dependent on barometric pressure.

Effect of Temperature on Oxygen Concentration

The ideal gas law, equation (1), shows that absolute gas concentration decreases by 0.341 % for a 1 C increase in temperature from 20 C (1 K / 293 K = 0.00341). For a sensor that measures absolute gas concentration, but is calibrated to read out in relative units, a 1 C temperature increase from 20 C results in an apparent decrease of 0.0714 % O₂ (0.341 % * 0.2095 = 0.0714 %) and a relative oxygen concentration of 20.878 %. As with barometric pressure, to obtain accurate oxygen measurements with a sensor that is calibrated to read relative oxygen concentration, a correction should be applied to compensate for temperature effects. The equation to correct relative oxygen measurements in air for temperature effects is:

$$O_2 = O_{2M} \left(\frac{T_M}{T_C} \right) \quad (7)$$

where O_{2M} is as given above, T_C is air temperature [K] at calibration, and T_M is air temperature [K] at the time of measurement (note that temperatures in equation (7) must be in K). The effects of temperature on relative oxygen concentration measurements, based on calculations from equation (7), are plotted in the figure below to show the significance of measuring and correcting for temperature. If not accounted for, temperature fluctuations show up in the measurement as an apparent change in relative oxygen concentration because sensors respond to absolute oxygen concentration, but are calibrated to read out in relative units.

Sensor Response to Temperature

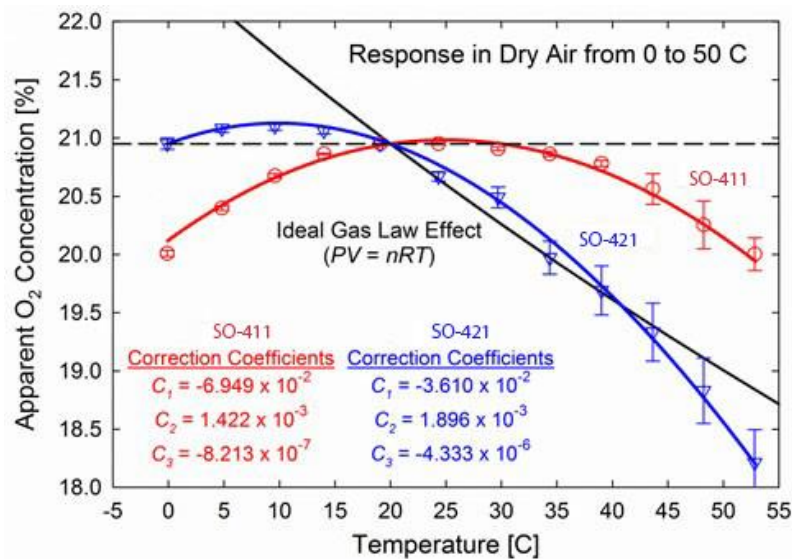
In practice, equation (7) does not accurately correct for temperature effects because in addition to the ideal gas law temperature effect, sensor electronics are affected by temperature. The combination of these two effects on Apogee oxygen sensors (SO-400 series) was determined from measurements in dry air across a wide temperature range by plotting pressure-corrected apparent oxygen concentration (i.e., measured oxygen concentration before temperature correction was applied) versus measured sensor temperature (T_s). The SO-400 series does not follow the ideal gas law response, thus, an empirical correction derived from measured data must be applied to account for both the ideal gas law and sensor electronics responses:

$$O_2 = O_{2M} + C_3 T_s^3 + C_2 T_s^2 + C_1 T_s + C_0 \quad (8)$$

where T_s is measured sensor temperature [C] (Apogee oxygen sensors come with a thermistor temperature reference sensor); coefficients C_3 , C_2 , and C_1 are listed in the figure below for the SO-400 series sensors; and C_0 is the offset coefficient calculated from measured temperature at calibration (T_c , in C):

$$C_0 = -(C_3 T_c^3 + C_2 T_c^2 + C_1 T_c). \quad (9)$$

The temperature effect on sensor electronics is slightly variable from sensor to sensor, thus, coefficients derived (average of three replicate sensors; error bars representing two standard deviations are shown in figure) may not yield the most accurate temperature correction for all sensors of the same model.



Empirically-measured temperature responses of the SO-411 and SO-421 series oxygen sensors, with third order polynomials fit to data, compared to the theoretical temperature response calculated from the ideal gas law, equation (1). The difference between theoretical and measured responses is due to a temperature effect on sensor electronics. The polynomial coefficients used to correct for the temperature response with equation (8) are listed. An offset coefficient (C_0) is not listed because it is dependent on temperature at calibration. It is calculated with equation (9). Sensors were calibrated at 20 C. As with barometric pressure, absolute oxygen concentration, thus, oxygen sensor output, varies with temperature. As temperature changes, relative oxygen concentration remains constant at 20.95 %, but an apparent oxygen change is measured if the temperature correction is not applied to relative measurements.

Effect of Humidity on Oxygen Concentration

As absolute humidity in the atmosphere increases, water vapor molecules displace and dilute other gas molecules. This causes the signal output of a gas sensor to decrease. The water vapor effect on relative oxygen concentration as a function of relative humidity (RH) and at a constant temperature is a linear decrease with increasing RH, as shown in the figure below. Conversely, the effect as a function of temperature at constant RH is a curvilinear decrease with increasing temperature, essentially the inverse of the slope of vapor pressure curves from a psychrometric chart. Even though water vapor molecules dilute and displace oxygen molecules, and cause an actual and not an apparent decrease in relative oxygen concentration, humidity effects are often accounted for to yield relative oxygen concentrations for a dry atmosphere. The equation to correct for humidity effects is:

$$O_2 = O_{2M} \left(\frac{P_C + (e_{AM} - e_{AC})}{P_C} \right) \quad (10)$$

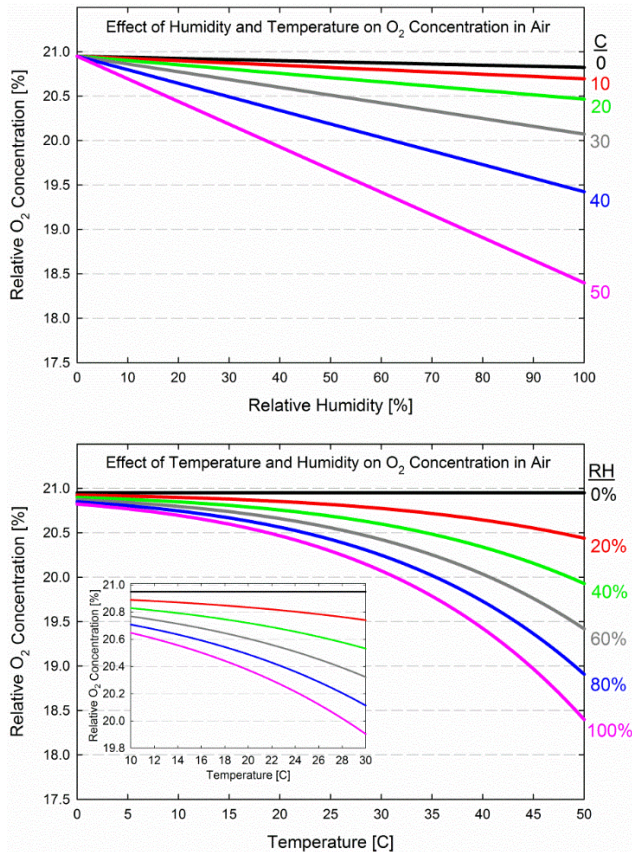
where P_C is barometric pressure at calibration [kPa], e_{AM} is vapor pressure [kPa] of air at the time of measurement, and e_{AC} is vapor pressure [kPa] of air at calibration. Vapor pressures in equation (10) are calculated from:

$$e_A = e_S \left(\frac{RH}{100} \right) \quad (11)$$

where RH is in % and e_S is saturation vapor pressure [kPa] of air calculated from air temperature (T_A , in C):

$$e_S = 0.61121 \exp \left(\frac{T_A \left(18.678 - \frac{T_A}{234.5} \right)}{257.14 + T_A} \right). \quad (12)$$

In soil environments relative humidity is generally between 99 and 100 %, unless the soil is extremely dry (below the permanent wilting point of -1,500 kPa). Thus, the water vapor effect can be accounted for as a function of temperature by correcting oxygen measurements based on the shape of the curve for 100 % RH in the graph below.



A) Relative humidity effects on relative oxygen concentration shown as a function of relative humidity at temperatures increments of 10 C and

B) as a function of temperature at relative humidity increments of 20 %. The air in soil is typically always saturated with water vapor (100 % relative humidity) unless the soil is very dry.

As with temperature, humidity also causes a slight effect on the sensor electronics. For measurements in soil or saturated air (100 % relative humidity), it is recommended that Apogee oxygen sensors are calibrated in conditions where relative humidity is 100 %. A simple way to accomplish this is to mount the sensor in a sealed chamber over water, with ambient air filling the headspace, as shown below.



Apogee oxygen sensor mounted in a sealed chamber over water. For measurements in environments where relative humidity is 100 %, sensors should be calibrated in conditions where relative humidity is 100 % in order to account for any humidity effects on sensor electronics.

Heating Sensor with Internal Heater

All Apogee oxygen sensors are equipped with an internal resistance heater. The heater is designed to maintain the temperature of the sensing element at approximately 2 C above ambient temperature in condensing (100 % relative humidity) environments (e.g., soil). Heating the sensing element keeps condensation from forming on the membrane, which would block the oxygen diffusion path and result in erroneous measurements. To operate the heater, apply continuous 12 V DC across the white (positive) and green (negative) wires.

SDI-12 Interface

The following is a brief explanation of the serial digital interface SDI-12 protocol instructions used in Apogee SO-400 series oxygen sensors. For questions on the implementation of this protocol, please refer to the official version of the SDI-12 protocol: <http://www.sdi-12.org/specification.php> (version 1.4, August 10, 2016).

Overview

During normal communication, the data recorder sends a packet of data to the sensor that consists of an address and a command. Then, the sensor sends a response. In the following descriptions, SDI-12 commands and responses are enclosed in quotes. The SDI-12 address and the command/response terminators are defined as follows:

Sensors come from the factory with the address of “0” for use in single sensor systems. Addresses “1 to 9” and “A to Z”, or “a to z”, can be used for additional sensors connected to the same SDI-12 bus.

“!” is the last character of a command instruction. In order to be compliant with SDI-12 protocol, all commands must be terminated with a “!”. SDI-12 language supports a variety of commands. Supported commands for the Apogee Instruments SO-400 oxygen sensors are listed in the following table (“a” is the sensor address. The following ASCII Characters are valid addresses: “0-9” or “A-Z”).

Supported Commands for Apogee Instruments SO-400 Series Oxygen Sensors

Instruction Name	Instruction Syntax	Description
Send Identification Command	a!	Send Identification Information
Measurement Command	aM!	Tells the Sensor to take a Measurement
Measurement Command w/ Check Character	aMC!	Tells the Sensor to take a Measurement and return it with a Check Character
Change Address Command	aAb!	Changes the Address of the Sensor from a to b
Concurrent Measurement Command	aC!	Used to take a measurement when more than one sensor is used on the same data line
Concurrent Measurement Command w/ Check Character	aCC!	Used to take a measurement when more than one sensor is used on the same data line. Data is returned with a check character.
Address Query Command	?!	Used when the address is unknown to have the sensor identify its address
Get Data Command	aD!	Retrieves the data from a sensor
Calibration Commands	aXxxx!	Used to calibrate the output of the sensor to the units desired by the user
Running Average Command	aXAVG!	Returns or sets the running average for sensor measurements.

Make Measurement Command: M!

The make measurement command signals a measurement sequence to be performed. Data values generated in response to this command are stored in the sensor's buffer for subsequent collection using "D" commands. Data will be retained in sensor storage until another "M", "C", or "V" command is executed. M commands are shown in the following examples:

Command	Response	Response to OD0!
aM! or aM0!	a0013<cr><lf>	Calibrated oxygen, sensor mV, sensor body temperature
aM1!	a0011<cr><lf>	Calibrated oxygen percent corrected for temperature
aMC!	a0013<cr><lf>	Calibrated oxygen, sensor mV, sensor body temperature w/ CRC
aMC1!	a0011<cr><lf>	Calibrated oxygen percent corrected for temperature w/CRC

where a is the sensor address ("0-9", "A-Z", "a-z") and M is an upper-case ASCII character.

The Calibrated Oxygen, Sensor mV, and Sensor Temperature are separated by the sign "+" or "-", as in the following example (0 is the address):

Command	Sensor Response	Sensor Response when data is ready
0M!	00013<cr><lf>	0<cr><lf>
0D0!	0+20.95+50.123+25.456<cr><lf>	
0M1!	00011<cr><lf>	0<cr><lf>
0D0!	0+20.95<cr><lf>	

where 20.95 is calibrated oxygen output (units as set by user using the appropriate extended command), 50.123 is the sensor mV, and 25.456 is sensor body temperature.

Concurrent Measurement Command: aC!

A concurrent measurement is one which occurs while other SDI-12 sensors on the bus are also making measurements. This command is similar to the "aM!" command, however, the nn field has an extra digit and the sensor does not issue a service request when it has completed the measurement. Communicating with other sensors will NOT abort a concurrent measurement. Data values generated in response to this command are stored in the sensor's buffer for subsequent collection using "D" commands. The data will be retained in the sensor until another "M", "C", or "V" command is executed:

Command	Response	Response to OD0!
aC! or aC0!	a00103<cr><lf>	Calibrated oxygen, sensor mV, sensor temperature
aC1!	a00101<cr><lf>	Calibrated oxygen percent corrected for temperature
aCC!	a00103<cr><lf>	Calibrated oxygen, sensor mV, sensor temperature w/ CRC
aCC1!	a00101<cr><lf>	Calibrated oxygen percent corrected for temperature w/CRC

where a is the sensor address ("0-9", "A-Z", "a-z", "*", "?") and C is an upper-case ASCII character.

For example (0 is the address):

Command	Sensor Response
0C!	000103<cr><lf>
0D0!	0+20.95+50.123+25.456<cr><lf>
0C1!	000101<cr><lf>
0D10!	0+20.95<cr><lf>

where 20.95 is calibrated oxygen output (units as set by user using the appropriate extended command), 50.123 is the sensor mV and 25.456 is sensor body temperature.

Change Sensor Address: aAb!

The change sensor address command allows the sensor address to be changed. If multiple SDI-12 devices are on the same bus, each device will require a unique SDI-12 address. For example, two SDI-12 sensors with the factory address of 0 requires changing the address on one of the sensors to a non-zero value in order for both sensors to communicate properly on the same channel:

Command	Response	Description
aAb!	b<cr><lf>	Change the address of the sensor

where a is the current (old) sensor address ("0-9", "A-Z"), A is an upper-case ASCII character denoting the instruction for changing the address, b is the new sensor address to be programmed ("0-9", "A-Z"), and ! is the standard character to execute the command. If the address change is successful, the datalogger will respond with the new address and a <cr><lf>.

Send Identification Command: a!

The send identification command responds with sensor vendor, model, and version data. Any measurement data in the sensor's buffer is not disturbed:

Command	Response	Description
"a!"	a13Apogee SO-4mmvvvx...xx<cr><lf>	The sensor serial number and other identifying values are returned

where a is the sensor address ("0-9", "A-Z", "a-z", "*", "?"), mm is a the sensor model number (10, 20), vv is a three character field specifying the sensor version number, and xx...xx is serial number.

Running Average Command

The running average command can be used to set or query the number of measurements that are averaged together before returning a value from a M! or MC! command. For example, if a user sends the command "OXAVG10!" to sensor with address 0, that sensor will average 10 measurements before sending the averaged value to the logger. To turn off averaging, the user should send the command "aXAVG1" to the sensor. To query the sensor to see how many measurements are being averaged, send the command "aXAVG!" and the sensor will return the number of measurements being averaged (see table below). The default for sensors is to have averaging turned off.

Command Name	Characters Sent	Response	Description
Query running Average	aXAVG!	an	a = sensor address, n = number of measurements used in average calculation. Note: n may be multiple digits.
Set running Average	aXAVGn!	a	a = sensor address, n = number of measurements to be used in average calculation. Note: n may be any value from 1 to 100.

Extended commands for calibration

Send Calibration Coefficients: aXCFZ!

This command sets the user-derived multiplier (slope) and offset (intercept) of the sensor output. Sent with this command needs to be the multiplier in the units the user wishes to have the sensor output and the offset in mV.

Command	Response	Description
"aXCFZ+m.mmmm+o.o!"	a<cr><lf>	Set the multiplier and offset.

where a is the sensor address ("0-9", "A-Z", "a-z", "*", "?"), +m.mmm is the multiplier and +o.oo is the offset in mV.

Set Zero Offset: aXZERO!

This command sets the zero offset of the sensor. The zero is set to the current mV measurement of the sensor. Before sending this command the sensor should be exposed to Nitrogen gas long enough for the sensor to equilibrate.

Command	Response	Description
"aXZERO!"	a<cr><lf>	Set the zero offset

where a is the sensor address ("0-9", "A-Z", "a-z", "*", "?").

Set Ambient Air – Relative Multiplier: aXAMBR!

This command sets the multiplier of the sensor. The multiplier is set using the current mV measurement of the sensor. The multiplier is calculated assuming ambient air conditions. This command sets the output to units of % Oxygen.

Command	Response	Description
"aXAMBR!"	a<cr><lf>	Set the multiplier

where a is the sensor address ("0-9", "A-Z", "a-z", "*", "?").

Set 100% Oxygen Multiplier: aXONEH!

This command sets the multiplier of the sensor. The multiplier is set using the current mV measurement of the sensor. The multiplier is calculated assuming 100% Oxygen connected to the sensor. This command sets the output to units of % Oxygen.

Command	Response	Description
"aXONEH!"	a<cr><lf>	Set the multiplier

where a is the sensor address ("0-9", "A-Z", "a-z", "*", "?").

Set Ambient Air – Absolute Multiplier: aXAMBA+pp.ppp!

This command sets the multiplier of the sensor so that the output is in units of absolute oxygen. Sent with this command needs to be the current pressure in the units the user wishes to have the sensor output. For example, if the units of pressure is in kPa the units of the calibrated oxygen from the M! or C! commands is in kPa. The multiplier is calculated assuming ambient air conditions.

Command	Response	Description
"aXAMBA+pp.ppp!"	a<cr><lf>	Set the multiplier

where a is the sensor address ("0-9", "A-Z", "a-z", "*", "?") and pp.ppp is the pressure.

For example (0 is the address):

Command	Sensor Response
0XAMBA+100.12!	0<cr><lf>

Where 100.12 is the pressure in the units chosen by the user.

Metadata Commands

Identify Measurement Commands

The Identify Measurement Commands can be used to view the command response without making a measurement. The command response indicates the time it takes to make the measurement and the number of data values that it returns. It works with the Verification Command (aV!), Measurement Commands (aM!, aM1! ... aM9!, aMC!, aMC1! ... aMC9!), and Concurrent Measurement Commands (aC!, aC1! ... aC9! , aCC!, aCC1! ... aCC9!).

The format of the Identify Measurement Command is the address, the capital letter I, the measurement command, and the command terminator ("!"), as follows:

<address>I<command>!

The format of the response is the same as if the sensor is making a measurement. For the Verification Command and Measurement Commands, the response is attn<CR><LF>. For the C Command, it is attnn<CR><LF>. For the High Volume Commands, it is attnnn<CR><LF>. The address is indicated by a, the time in seconds to make the measurement is indicated by ttt, and the number of measurements is indicated by n, nn, and nnn. The response is terminated with a Carriage Return (<CR>) and Line Feed (<LF>).

Identify Measurement Command example:

3IMC2!	The Identify Measurement Command for sensor address 3, M2 command, requesting a CRC.
30032<CR><LF>	The response from sensor address three indicating that the measurement will take three seconds and two data values will be returned.

Identify Measurement Parameter Commands

The Measurement Parameter Commands can be used to retrieve information about each data value that a command returns. The first value returned is a Standard Hydrometeorological Exchange Format (SHEF) code. SHEF codes are published by the National Oceanic and Atmospheric Administration (NOAA). The SHEF code manual can be found at <http://www.nws.noaa.gov/oh/hrl/shef/indexshef.htm>. The second value is the units of the parameter. Additional fields with more information are optional.

The Measurement Parameter Commands work with the Verification Command (aV!), Measurement Commands (aM!, aM1! ... aM9!, aMC!, aMC1! ... aMC9!), and Concurrent Measurement Commands (aC!, aC1! ... aC9! , aCC!, aCC1! ... aCC9!).

The format of the Identify Measurement Parameter Command is the address, the capital letter I, the measurement command, the underscore character (“_”), a three-digit decimal number, and the command terminator (“!”). The three-digit decimal indicates which number of measurement that the command returns, starting with “001” and continuing to “002” and so on, up to the number of measurements that the command returns.

`<address>I<command>_<three-digit decimal>!`

The format of the response is comma delimited and terminated with a semicolon. The first value is the address. The second value is the SHEF code. The third value is the units. Other optional values may appear, such as a description of the data value. The response is terminated with a Carriage Return (<CR>) and Line Feed (<LF>).

`a,<SHEF Code>,<units>;<CR><LF>`

Identify Measurement Parameter Command example:

<code>1IC_001!</code>	The Identify Measurement Parameter Command for sensor address 1, C command, data value 1.
<code>1,RW,Watts/meter squared,incoming solar radiation;<CR><LF></code>	The response from sensor address 1, SHEF code RW, units of Watts/meter squared, and additional information of incoming solar radiation.

MAINTENANCE AND RECALIBRATION

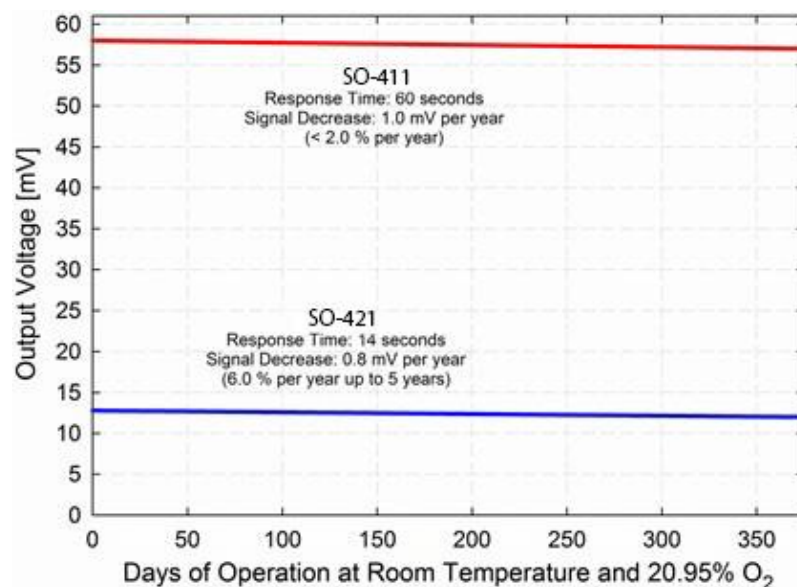
Visual inspection of the Teflon membrane should be made periodically to verify that the oxygen path is free from obstruction, as shown below. Avoid placing sharp objects inside the sensor opening, as the membrane can easily be punctured.



Life Expectancy

Life expectancy of the SO-411 and SO-421 sensors is approximately ten and five years of continuous use in 20.95 % oxygen at 20 C, respectively. Lifetime can be lengthened by storing sensors in cold temperatures (e.g., fridge or freezer) when not in use.

Sensor recalibration can be conducted periodically and should be determined by the level of measurement accuracy required for the application. Sensor signal decrease over one year when exposed to 20.95 % oxygen is shown in the figure below. SO-411 sensors decrease by approximately 1 mV per year and SO-421 sensors decrease by approximately 0.8 mV per year, or approximately 2 % of signal output at 20.95 % oxygen (SO-411) and 6 % of signal output at 20.95 % oxygen (SO-421). This signal decrease yields increases in calibration factor of approximately 2% for SO-411 and 6 % for SO-421 sensors.



Long-term stability (output voltage decrease over time) of Apogee SO-400 series oxygen sensors. The response time and signal decrease for both series are also listed.

Sensor Storage

To prolong the life expectancy of Apogee sensors, storage at low temperature (in a refrigerator) and at low oxygen concentration is recommended. Care should be taken to not short the positive and negative leads for the O₂ sensor as this may have an effect on the response time to oxygen.

If the sensor is stored in a 0% O₂ environment for an extended period of time, the sensor's offset becomes lower and response speed to O₂ will become slower. In this case, the sensor will be able to recover to normal response speed after exposure to a normal environment for a period of 24 hours.

Helpful Links

For tips on how to make calibration corrections for changes in environmental conditions, check out our technical support video at <https://youtu.be/xnlyjfzFpa0>.

For more information on sensor operation and calibration, as well as a link to the oxygen readings calculator, go to <https://www.apogeeinstruments.com/oxygen-sensor-support/>.

TROUBLESHOOTING AND CUSTOMER SUPPORT

Independent Verification of Functionality

The oxygen sensing element inside Apogee SO-400 series oxygen sensors outputs a voltage signal proportional to partial pressure of gaseous oxygen. Connect the sensor to a compatible datalogger and send the M1! Command the first result is the sensor output in mV. SO-400 series sensors should read approximately 60 mV at sea level in ambient air (20.95 % O₂). These voltages will decrease by approximately 1 % per 100 meters of elevation increase above sea level.

If the sensor does not communicate with the datalogger, use an ammeter to check the current drain. It should be near 0.6 mA when the sensor is not communicating and spike to approximately 1.3 mA when the sensor is communicating. Any current drain greater than approximately 6 mA indicates a problem with power supply to the sensors, wiring of the sensor, or sensor electronics.

Compatible Measurement Devices (Dataloggers/Controllers/Meters)

Any datalogger or meter with SDI-12 functionality that includes the M or C command.

An example datalogger program for Campbell Scientific dataloggers can be found on the Apogee webpage at <http://www.apogeeinstruments.com/content/Oxygen-Sensor-Digital.CR1>.

Modifying Cable Length

SDI-12 protocol limits cable length to 60 meters. For multiple sensors connected to the same data line, the maximum is 600 meters of total cable (e.g., ten sensors with 60 meters of cable per sensor). See Apogee webpage for details on how to extend sensor cable length (<http://www.apogeeinstruments.com/how-to-make-a-weatherproof-cable-splice/>).

RETURN AND WARRANTY POLICY

RETURN POLICY

Apogee Instruments will accept returns within 30 days of purchase as long as the product is in new condition (to be determined by Apogee). Returns are subject to a 10 % restocking fee.

WARRANTY POLICY

What is Covered

All products manufactured by Apogee Instruments are warranted to be free from defects in materials and craftsmanship for a period of four (4) years from the date of shipment from our factory. To be considered for warranty coverage an item must be evaluated by Apogee.

Products not manufactured by Apogee (spectroradiometers, chlorophyll content meters, EE08-SS probes) are covered for a period of one (1) year.

What is Not Covered

The customer is responsible for all costs associated with the removal, reinstallation, and shipping of suspected warranty items to our factory.

The warranty does not cover equipment that has been damaged due to the following conditions:

1. Improper installation or abuse.
2. Operation of the instrument outside of its specified operating range.
3. Natural occurrences such as lightning, fire, etc.
4. Unauthorized modification.
5. Improper or unauthorized repair.

Please note that nominal accuracy drift is normal over time. Routine recalibration of sensors/meters is considered part of proper maintenance and is not covered under warranty.

Who is Covered

This warranty covers the original purchaser of the product or other party who may own it during the warranty period.

What Apogee Will Do

At no charge Apogee will:

1. Either repair or replace (at our discretion) the item under warranty.
2. Ship the item back to the customer by the carrier of our choice.

Different or expedited shipping methods will be at the customer's expense.

How To Return An Item

1. Please do not send any products back to Apogee Instruments until you have received a Return Merchandise

Authorization (RMA) number from our technical support department by submitting an online RMA form at www.apogeeinstruments.com/tech-support-recalibration-repairs/. We will use your RMA number for tracking of the service item. Call (435) 245-8012 or email techsupport@apogeeinstruments.com with questions.

2. For warranty evaluations, send all RMA sensors and meters back in the following condition: Clean the sensor's exterior and cord. Do not modify the sensors or wires, including splicing, cutting wire leads, etc. If a connector has been attached to the cable end, please include the mating connector – otherwise the sensor connector will be removed in order to complete the repair/recalibration. **Note:** *When sending back sensors for routine calibration that have Apogee's standard stainless-steel connectors, you only need to send the sensor with the 30 cm section of cable and one-half of the connector. We have mating connectors at our factory that can be used for calibrating the sensor.*

3. Please write the RMA number on the outside of the shipping container.

4. Return the item with freight pre-paid and fully insured to our factory address shown below. We are not responsible for any costs associated with the transportation of products across international borders.

Apogee Instruments, Inc.
721 West 1800 North Logan, UT
84321, USA

5. Upon receipt, Apogee Instruments will determine the cause of failure. If the product is found to be defective in terms of operation to the published specifications due to a failure of product materials or craftsmanship, Apogee Instruments will repair or replace the items free of charge. If it is determined that your product is not covered under warranty, you will be informed and given an estimated repair/replacement cost.

PRODUCTS BEYOND THE WARRANTY PERIOD

For issues with sensors beyond the warranty period, please contact Apogee at techsupport@apogeeinstruments.com to discuss repair or replacement options.

OTHER TERMS

The available remedy of defects under this warranty is for the repair or replacement of the original product, and Apogee Instruments is not responsible for any direct, indirect, incidental, or consequential damages, including but not limited to loss of income, loss of revenue, loss of profit, loss of data, loss of wages, loss of time, loss of sales, accrual of debts or expenses, injury to personal property, or injury to any person or any other type of damage or loss.

This limited warranty and any disputes arising out of or in connection with this limited warranty ("Disputes") shall be governed by the laws of the State of Utah, USA, excluding conflicts of law principles and excluding the Convention for the International Sale of Goods. The courts located in the State of Utah, USA, shall have exclusive jurisdiction over any Disputes.

This limited warranty gives you specific legal rights, and you may also have other rights, which vary from state to state and jurisdiction to jurisdiction, and which shall not be affected by this limited warranty. This warranty extends only to you and cannot be transferred or assigned. If any provision of this limited warranty is unlawful, void or unenforceable, that provision shall be deemed severable and shall not affect any remaining provisions. In case of any inconsistency between the English and other versions of this limited warranty, the English version shall prevail.

This warranty cannot be changed, assumed, or amended by any other person or agreement

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